

A comparison study of geostatistical simulation for predicting soil texture

Yong He^{1, 2}, Hong Wang¹, Ke Lin. Hu², Yuan Fang Huang², Bao Guo Li², Bing Si³ and Brandt Kelsey¹

¹Box 1030, Swift Current, Saskatchewan S9H 3X2 *;²Department of Soil and Water Sciences, China Agricultural University, Beijing 100193, P.R. China;

³Department of Soil Science, University of Saskatchewan, Saskatchewan, S7N 5A8, Canada



Introduction

Soil texture controls many important ecological, hydrological, and geomorphic processes. To predict the spatial distribution of soil texture, three-dimensional (3-D) geostatistical modeling is an important approach.

Materials & methods

The study area is located near the Quzhou Experimental Station, China Agricultural University, Hebei Province (36° 51' N, 115° 3' E) in central North China Plain. Most of the area is flat, located in a loamy depression in the Zhang River's alluvial fan. Soils are saline to varying degrees and derived from recent alluvial deposits. These soils are typically composed of layers originally deposited under flood conditions.

In this study, sequential indicator simulation (SIS) and transition probability indicator simulation (TPROGS) were used for predicting soil texture in an area of the Zhang River's alluvial fan. A total of 139 soil profiles (Fig. 1) were sampled at intervals of 350 m from west to east, 300 m from north to south and 0.05 m in the vertical direction to a depth of 2 m covering 15 km² area.

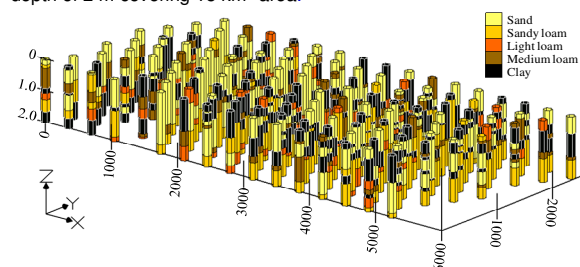


Fig. 1. Three-Dimensional exhibition of measured soil profiles (Distance=m)

Results & discussions

Training results (Fig 2) showed that auto-variograms (SIS) fitted the observations well in the vertical direction, but poorly in the horizontal direction, while the auto-transition probability (TPROGS) fitted well in both directions.

Results & discussions

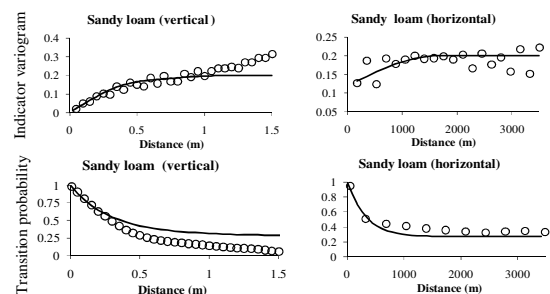


Fig. 2. Auto-indicator variogram and auto-transition probability (circles) and their corresponding fitted models (solid lines)

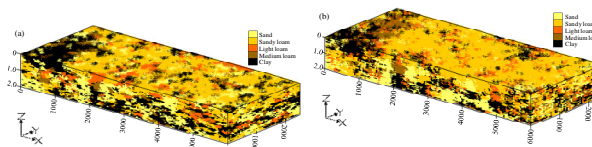


Fig. 3. Three-Dimensional realizations (10) for SIS (a) and TPROGS (b) (Distance=m)

Visually, predictions obtained from SIS and TPROGS are relatively consistent with the observed data (Fig. 3).

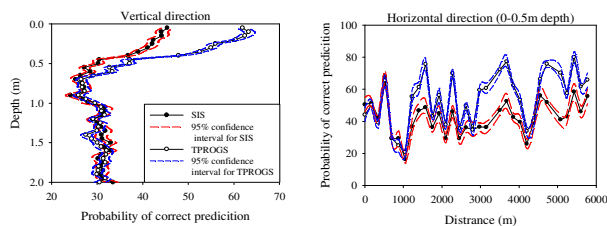


Fig. 4. Probability of correct prediction in vertical and horizontal direction obtained from SIS and TPROGS modes

Results & discussions

The TPROGS model slightly improved (3.6%) overall predictions compared to SIS. Both SIS and TPROGS models predicted soil texture classes near soil surface (0-0.5 m) better than that in the deep depth (0.5-2.0 m) (Fig. 4). However, the TPROGS model improved the prediction in the top soil indicating that the TPROGS can capture the variability of soil textures in vertical direction more efficiently than SIS.

Conclusion

•The TPROGS model performed better than SIS for the near-surface (0-0.5 m) soils. It seems that under the circumstances of this study, TPROGS is a better model for predicting soil texture.

•Both models poorly predicted light loam and medium loam, probably because the portions of light loam and medium loam in this study are very low (<10%).

•Further improvement in modeling, however, is needed as only less than half of the total predictions were correct for the TPROGS model.

Main references

- Carle, S.F., Fogg, G.E., 1996. Transition probability-based indicator geostatistics. *Mathematical Geology* 28, 453–476.
- Deutsch, C.V., Journel, A.G., 1998. *GSLIB: Geostatistical Software Library and User's Guide*. Oxford University Press, Oxford.
- He, Y., Chen, D., Li, B.G., Huang, Y.F., Hu, K.L., Li, Y., Willett, I., 2009. Sequential indicator simulation and indicator kriging estimation of three dimensional soil textures. *Australia Journal of soil research* 47, 622–631.
- Zhang, C.R., Li, W.D., 2008. Regional-scale modelling of the spatial distribution of surface and subsurface textural classes in alluvial soils using Markov chain geostatistics. *Soil use and management* 24, 263–272.

Acknowledgment

We gratefully acknowledge support for this research from the Visiting Fellowships in Canadian Government Laboratories Program, managed by the natural Science and Engineering Research Council of Canada and. We are thankful to Dr. Weidong Li, Kent State University, for providing the data used in this paper. We also thank to Dr. Helen Suter, and Dr. Ian Willett, University of Melbourne, for their constructive comments.